

# Surrogates 7020

## Chapter 8B: Sensitivity Analysis

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# Sensitivity Analysis

- ▶ In any nonparametric regression setting, it's important to understand the role inputs play in predicted outputs.
- ▶ When inputs change, how do outputs change?
- ▶ In simple linear regression, estimated slope coefficients and their standard errors speak volumes, resulting in t-tests or F-tests to ascertain relevance.
- ▶ By contrast, the effect of fitted GP hyperparameters and input settings on predictive surfaces is subtle and sometimes counter-intuitive. In a way, that's what nonparametric means: parameters don't unilaterally dictate what's going on.
- ▶ Model fits and predictive equations gain flexibility from data, sometimes with the help of – but equally often in spite of – any estimated tuning or hyperparameters.

# Uncertainty distribution

- ▶ If we're going to say how sensitive outputs are to changes in inputs, it makes sense to first say what inputs we expect/care about, and how much they themselves may change/vary.
- ▶ Underlying the Saltelli method is a reference distribution for  $\boldsymbol{x}$ , sometimes called an uncertainty distribution  $U(\boldsymbol{x})$ .
- ▶  $U$  can represent uncertainty about future values of  $\boldsymbol{x}$ , or the relative amount of research interest in various areas of the input space.
- ▶ In many applications, the uncertainty distribution is simply uniform over a bounded region.

# Uncertainty distribution

- ▶ In Bayesian optimization (Chapter 7),  $U$  can be used to express prior information from experimentalists or modelers on where to look for solutions.
- ▶ For example, when there's a large number of input variables over which an objective function is to be optimized, typically only a small subset will be influential within the confines of their uncertainty distribution.
- ▶ Sensitivity analysis can be used to reduce the volume of the search space of such optimizations (Taddy et al. 2009).
- ▶ In the case of observational systems such as air-quality or smog levels,  $U(\mathbf{x})$  may derive from an estimate of the density governing natural occurrence of  $\mathbf{x}$  factors, e.g., air pressure, temperature, wind and cloud cover.
- ▶ In such scenarios, sensitivity analysis attempts to resolve natural variability in responses  $Y(\mathbf{x})$ .

## Assume for the moment independent

We treat here the standard and computationally convenient independent specification,

$$U(\boldsymbol{x}) = \prod_{k=1}^m u_k(\boldsymbol{x}_k),$$

where  $u_k$ , for  $k = 1, \dots, m$ , represent densities assigned to the margins of  $\boldsymbol{x}$ . With  $U$  being specified probabilistically, readers may not be surprised to see sampling feature as a principal numerical device for averaging over uncertainties, i.e., over variability in  $U$ .

# Main Effects

The simplest sensitivity indices are main effects, which deterministically vary one input variable,  $j$ , while averaging others over  $U_{-j}$ :

$$\begin{aligned} me(\mathbf{x}_j) &\equiv E_{U_{-j}}(y|\mathbf{x}_j) \\ &= \int \int_{X_{-j}} yp(y|x_1, \dots, x_m) u_{-j}(x_1, x_{j-1}, x_{j+1}, x_m) dx_{-j} dy. \end{aligned}$$

Above,  $u_{-j} = \prod_{k \neq j} u_k(x_k)$  represents density derived from the joint distribution  $U$  without coordinate  $j$ , i.e.  $U_{-j}$  with  $X_{-j}$  and  $x_{-j}$  defined similarly, and

$p(y|x_1, \dots, x_m) \equiv p(Y|\mathbf{x}) \equiv p(Y(\mathbf{x}) = y)$  comes from the surrogate, e.g., a GP predictor.

# Calculating Main Effects

Algorithmically, calculating main effects proceeds as follows: grid out X-space in each coordinate with values  $x_{ji}$ , for  $i = 1, \dots, G$  say; gather  $me(x_{ji})$ -values holding the  $j$ th coordinate fixed at each  $x_{ji}$ , in turn, and average over the rest (and y) in an MC fashion; finally plot all  $me(x_{ji})$  on a common x-axis. A pseudocode in Algorithm 8.3 formalizes that sequence of steps with some added numerical detail. The algorithm utilizes samples of size  $N$  in its MC approximations.

## Main Effects or any other quantity

Although Eq. (8.5) and Algorithm 8.3 showcase mean main effects  $\mu(\mathbf{x}) = \int y p(y|\mathbf{x}) dy$ , any aspect of  $p(y|\mathbf{x})$  which may be expressed as an integral can be averaged with respect to  $U$  in this manner. Quantiles are popular, for example, since they may be plotted on the same axes as means.

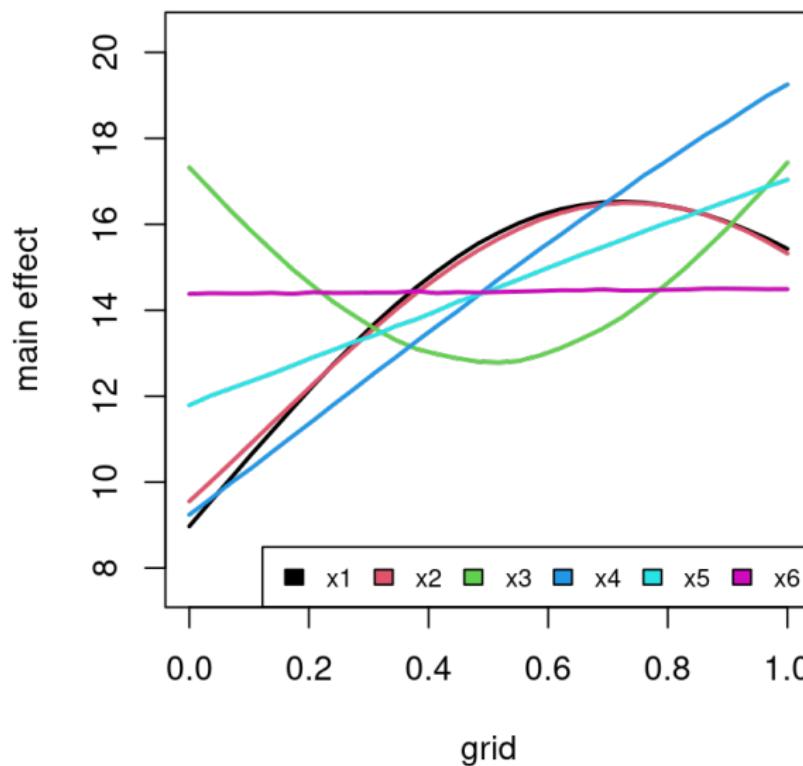


Figure: Mean main effects for Friedman data observed with irrelevant input  $x_6$ .